

Each problem is worth 10 points. For full credit indicate clearly how you reached your answer.

1. Give an example of eigenvalues that would produce a saddle at the origin.

a saddle occurs when  $\lambda_1 < 0 < \lambda_2$

so

$$\lambda_1 = -1$$

$$\lambda_2 = 1$$

will work.

Great

2. If you know that a planar system has eigenvalues  $\lambda_1 = 4$  and  $\lambda_2 = 0$ , with corresponding eigenvectors

$v_1 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$  and  $v_2 = \begin{pmatrix} 3 \\ 5 \end{pmatrix}$ , write a general solution for the system.

$$y(t) = e^{4t} \begin{pmatrix} 1 \\ -2 \end{pmatrix} + e^{0t} \begin{pmatrix} 3 \\ 5 \end{pmatrix}$$

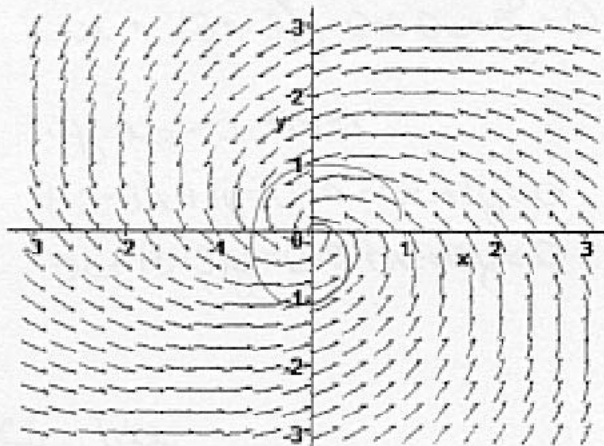
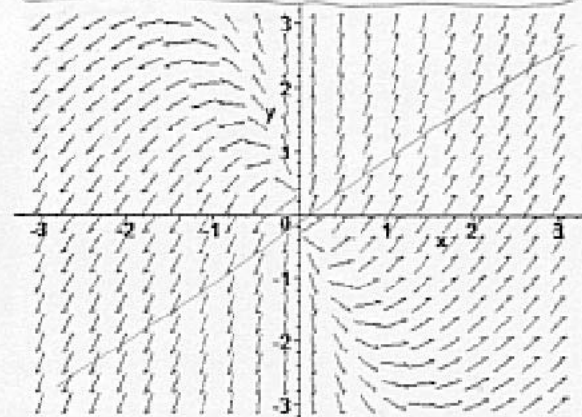
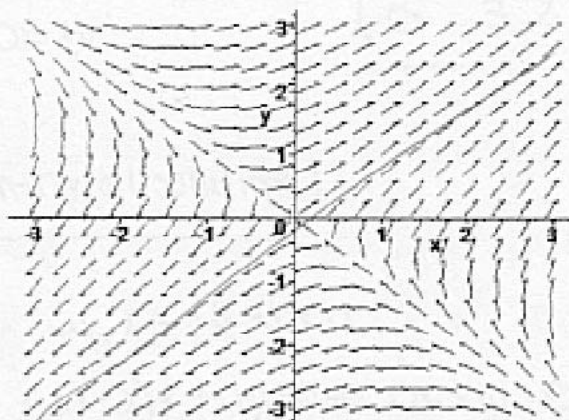
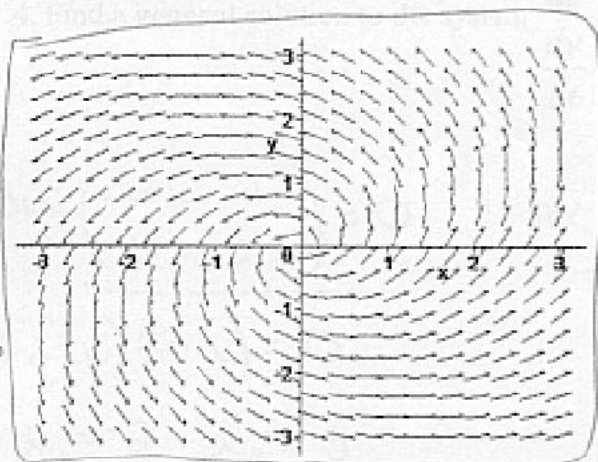
$$y(t) = e^{4t} \begin{pmatrix} 1 \\ -2 \end{pmatrix} + \begin{pmatrix} 3 \\ 5 \end{pmatrix} \leftarrow \text{specific sol.}$$

to make general add coeff.

$$y(t) = k_1 e^{4t} \begin{pmatrix} 1 \\ -2 \end{pmatrix} + k_2 \begin{pmatrix} 3 \\ 5 \end{pmatrix}$$

Excellent

3. Which of the phase planes shown below could correspond to a planar system with eigenvalues  $\lambda_1 = 2 + i$  and  $\lambda_2 = 2 - i$ ?



sink

For complex lambda values w/ a real part, we must analyze as follows:  
 $\lambda = \alpha \pm \beta i$

\*  $\alpha > 0$  so it's a spiral source

\*  $\beta = 1$

Excellent

4. Find a general solution to the system

$$\begin{aligned} \frac{dx}{dt} &= -2x + y \\ \frac{dy}{dt} &= 0x + 3y \end{aligned}$$

$$A = \begin{pmatrix} -2 & 1 \\ 0 & 3 \end{pmatrix}$$

\*  $\det \begin{pmatrix} -2-\lambda & 1 \\ 0 & 3-\lambda \end{pmatrix} = 0$  (\* for nontrivial solutions)

$$(-2-\lambda)(3-\lambda) = 0$$

$$\lambda_1 = -2 \quad \lambda_2 = 3$$

if  $\lambda_1 = -2$  then

$$\begin{aligned} (-2+2)x + 1y &= 0 \Rightarrow 0x + 1y = 0 \\ 0x + (3+2)y &= 0 \Rightarrow 0x + 5y = 0 \end{aligned} \quad \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

if  $\lambda_2 = 3$  then

$$\begin{aligned} (-2-3)x + 1y &= 0 \Rightarrow -5x + 1y = 0 \\ 0x + (3-3)y &= 0 \Rightarrow 0x + 0y = 0 \end{aligned} \quad \begin{pmatrix} 1 \\ 5 \end{pmatrix}$$

so a general solution looks like

$$\vec{y}(t) = k_1 e^{-2t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + k_2 e^{3t} \begin{pmatrix} 1 \\ 5 \end{pmatrix}$$

Well done

5. The planar system  $\begin{cases} \frac{dx}{dt} = 2x - 3y \\ \frac{dy}{dt} = 3x + 2y \end{cases}$  has eigenvalues  $\lambda_1 = 2 + 3i$  and  $\lambda_2 = 2 - 3i$ , and corresponding eigenvectors  $\mathbf{v}_1 = \begin{pmatrix} 1 \\ -i \end{pmatrix}$  and  $\mathbf{v}_2 = \begin{pmatrix} 1 \\ i \end{pmatrix}$ . Write a general solution to this system in a form not involving imaginary exponents.

so for  $\lambda_1 = 2 + 3i$ :

$$Y(t) = k_1 e^{(2+3i)t} \begin{pmatrix} 1 \\ -i \end{pmatrix}$$

$$= e^{2t} e^{3it} \begin{pmatrix} 1 \\ -i \end{pmatrix} = e^{2t} (\cos 3t + i \sin 3t) \begin{pmatrix} 1 \\ -i \end{pmatrix}$$

$$= \begin{pmatrix} e^{2t} \cos 3t + i e^{2t} \sin 3t \\ -i e^{2t} \cos 3t + e^{2t} \sin 3t \end{pmatrix}$$

$$= e^{2t} \begin{pmatrix} \cos 3t \\ \sin 3t \end{pmatrix} + i e^{2t} \begin{pmatrix} \sin 3t \\ -\cos 3t \end{pmatrix}$$

Excellent

general form:

$$Y(t) = k_1 e^{2t} \begin{pmatrix} \cos 3t \\ \sin 3t \end{pmatrix} + k_2 e^{2t} \begin{pmatrix} \sin 3t \\ -\cos 3t \end{pmatrix}$$

6. For which values of the constant  $b$  will the system of differential equations  $\frac{dx}{dt} = 2x + by$  have condition  $Y_0 = (1, 0)$  solutions involving sine and cosine?

$$\det \begin{pmatrix} 2-\lambda & b \\ 4 & 6-\lambda \end{pmatrix} = 0 = \frac{(2-\lambda)(6-\lambda) - 4b}{1} = 12 - 8\lambda + \lambda^2 - 4b$$

$$0 = \lambda^2 - 8\lambda + (12 - 4b)$$

$$a = 1$$

$$b = -8$$

$$c = (12 - 4b)$$

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\lambda = \frac{8 \pm \sqrt{64 - 4(1)(12 - 4b)}}{2(1)}$$

To yield sines and cosines in the solution the eigenvalues must be complex. In order to obtain this the sum under the radical must be less than zero

$$= \frac{8 \pm \sqrt{64 - 48 + 16b}}{2} = \frac{8 \pm \sqrt{16 + 16b}}{2} = \frac{8 \pm \sqrt{16(1+b)}}{2} = \frac{8 \pm 4\sqrt{1+b}}{2}$$

$$= 4 \pm 2\sqrt{1+b}$$

$$\text{so } 1 + b < 0$$

$$\boxed{b < -1}$$

Nice  
Job



7. Find a particular solution to the planar system  $\frac{dY}{dt} = \begin{pmatrix} -2 & -1 \\ 1 & -4 \end{pmatrix} Y$  which satisfies the initial condition  $Y_0 = (1, 0)$ .

$$\det \begin{pmatrix} -2-\lambda & -1 \\ 1 & -4-\lambda \end{pmatrix} = 0 \quad (\text{for nontrivial solutions!})$$

$$(-2-\lambda)(-4-\lambda) + 1 = 0$$

$$8 + 4\lambda + 2\lambda + \lambda^2 + 1 = 0$$

$$\lambda^2 + 6\lambda + 9 = 0$$

$$(\lambda + 3)(\lambda + 3) = 0$$

$$\lambda = -3 \leftarrow \text{repeated eigenvalues!}$$

\*for repeated eigenvalues, we must use the solution form  
 of  $\vec{Y}(t) = e^{\lambda t} \vec{V}_0 + t e^{\lambda t} \vec{V}_1$ , where  $\vec{V}_1 = (A - \lambda I) * \vec{V}_0$ .

compute  $\vec{V}_1$ : 
$$\vec{V}_1 = \left[ \begin{pmatrix} -2 & -1 \\ 1 & -4 \end{pmatrix} + \begin{pmatrix} +3 & 0 \\ 0 & +3 \end{pmatrix} \right] \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$2 \times 2$        $2 \times 1$

$$\vec{V}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

so the solution is:

$$\vec{Y}(t) = e^{-3t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + t e^{-3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Wonderful

9. Convert the second-order differential equation to a system of first-order

8. Suppose that the planar system  $\frac{d\mathbf{Y}}{dt} = \begin{pmatrix} -0.2 & 0.1 \\ 0.0 & -0.1 \end{pmatrix} \mathbf{Y}$  represents the populations of two

species of fish, creatively labeled as "species X" and "species Y", where  $x(t)$  actually gives the number of fish of species X in a pond above or below the natural equilibrium population and  $y(t)$  gives the number of fish of species Y present in the pond.

$$x(t) = X - x_0 \qquad y(t) = y(t)$$

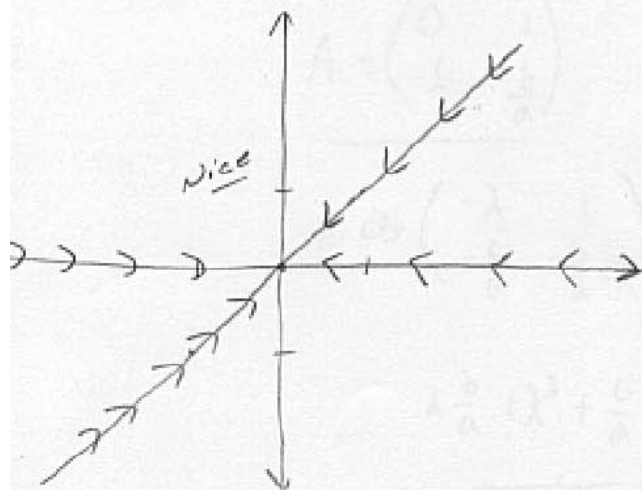
The eigenvalues of the system are  $\lambda_1 = -0.2$  and  $\lambda_2 = -0.1$ , with associated eigenvectors  $\mathbf{V}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

and  $\mathbf{V}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .

(a) Does the presence of fish of species Y benefit or hurt the population of species X?

(b) If all the fish of species Y are exterminated, what will happen to species X?

(c) If a small number of fish of species Y are introduced, with species X beginning at equilibrium, what will happen?



$$(a) \frac{dx}{dt} = -0.2x(t) + 0.1y(t)$$

it benefits the species X because the coefficient on y is positive

$$(b) \frac{dx}{dt} = -0.2x(t)$$

it will go to its own

equilibrium  $x_0$  because  $x(t) = X - x_0$

(c) so, if X is  $> x_0$  the pop. will decrease <sup>to  $x_0$</sup>  but if X is  $< x_0$  the pop. will increase to  $x_0$

(c) The y population will decrease until it completely dies off, but the X pop. will increase while the Y species is present until it dies off and then the X species will fall back to equilibrium.

Excellent

9. Convert the second-order differential equation  $ay'' + by' + cy = 0$  to a system of first-order equations and find the equation in  $\lambda$  whose roots are the eigenvalues of the system.

$$\text{Let } v = y'$$

$$\Rightarrow av' + bv + cy = 0 \Rightarrow v' = \left( \frac{-b}{a}v + \left( \frac{c}{a} \right)y \right)$$
$$\underline{\underline{y' = v}}$$

$$\underline{\underline{A = \begin{pmatrix} -\frac{b}{a} & -\frac{c}{a} \\ 1 & 0 \end{pmatrix}}}$$

$$\underline{\underline{\det \begin{pmatrix} -\frac{b}{a} - \lambda & -\frac{c}{a} \\ 1 & -\lambda \end{pmatrix} = 0}}$$

$$\lambda \left( \lambda + \frac{b}{a} \right) + \frac{c}{a} = 0$$

$$\lambda^2 + \frac{b}{a}\lambda + \frac{c}{a} = 0 \Rightarrow \underline{\underline{a\lambda^2 + b\lambda + c = 0}}$$

Nice.



10. Jon is trying to make up a problem for a differential equations test. He wants a planar system with eigenvalues 2 and 3, with respective eigenvectors  $\begin{pmatrix} 1 \\ 3 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . He knows that you can make a matrix with desired eigenvalues by putting the eigenvalues you want as entries on the main diagonal of the coefficient matrix with a zero in one of the other spots, but what coefficient matrix does he need in order to have his desired eigenvectors?

~~$$\begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} \quad \begin{pmatrix} 2-\lambda & 0 \\ 0 & 3-\lambda \end{pmatrix}$$

$$(2-\lambda)(3-\lambda) = 0$$

$$\lambda = 2, \lambda = 3$$

$$\lambda = 2: \quad 0x + 1y = 0 \quad \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\lambda = 3: \quad -1x + 0y = 0 \quad \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$~~

the solution to the system is:  $Y(t) = e^{2t} \begin{pmatrix} 1 \\ 3 \end{pmatrix} + e^{3t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

or  $x(t) = e^{2t}$   
 $y(t) = 3e^{2t} + e^{3t}$

so  $x'(t) = 2e^{2t}$   
 $y'(t) = 6e^{2t} + 3e^{3t}$

what coefficients on  $x + y$  will work?

$x'(t) = 2x + 0y$ ?  $2x - 0y = 2e^{2t}$  ✓

$y'(t) = 3y - 3x$ ?  $-3x + 3y = -3e^{2t} + 3(3e^{2t} + e^{3t}) = -3e^{2t} + 9e^{2t} + 3e^{3t} = 6e^{2t} + 3e^{3t}$  ✓

this works, so our coefficient matrix can be:

$$\begin{pmatrix} 2 & 0 \\ -3 & 3 \end{pmatrix}$$

Nice approach!