

$y(t)$ (see Figure 1.10).

of the differential equation yield the slopes of the tangents at all points on the graph of $y(t)$ satisfies the differential equation. In other words, the values of the right-hand side of the solution $y(t)$. The equality of dy/dt and $f(t, y)$ must hold for all t for which nothing special about the point (t_1, y_1) other than the fact that it is a point on the graph of $y(t)$ at the point (t_1, y_1) is $f(t_1, y_1)$ (see Figure 1.9). Note that there is the graph of $y(t)$ at the point (t_1, y_1) is $f(t_1, y_1)$ means that the slope of the tangent line to the derivative dy/dt at $t = t_1$ is given by the number $f(t_1, y_1)$. Geometrically, this through the point (t_1, y_1) where $y_1 = y(t_1)$, then the differential equation says that the derivative dy/dt at $t = t_1$ is $f(t_1, y_1)$. If the function $y(t)$ is a solution of the equation $dy/dt = f(t, y)$ and if its graph passes

The Geometry of $dy/dt = f(t, y)$

$$\frac{dy}{dt} = f(t, y).$$

graphs of the solutions to the differential equation techniques for representing solutions, and we develop a method for visualizing the equations are frequently easier to understand and use. In this section we focus on geometric. However, there are other ways to describe solutions, and these alternative representations often a useful way to describe a solution of a differential equation. Differential equation is often a useful way to describe a solution of a differential equation (in other words, finding a formula) for a solution to a dif-

1.3 QUALITATIVE TECHNIQUE: SLOPE FIELDS

mortgage at 5% compounded continuously, which is the better deal?

(c) If Ms. Lee can invest the \$4,500 she would have paid in points for the second

not invest the money she would have paid in points)?

(b) Which is a better deal over the entire time of the loan (assuming Ms. Lee does

(a) How much does Ms. Lee pay in each case?

$$\frac{dM}{dt} = iM - p.$$

Then the model for the amount owed is

$$p = \text{annual payment}.$$

i = annual interest rate, and

$$M(t) = \text{amount owed at time } t \text{ (measured in years)},$$

interest is compounded and payments are made continuously. Let

Ms. Lee to pay \$4,500 extra to get the loan). As an approximation, we assume that lender at the beginning of the loan. For example, a mortgage with 3 points requires 3 points. (A “point” is a fee of 1% of the loan amount that the borrower pays the year with no points, or she can borrow the money at 6.5% per year with a charge of 30-year mortgage and she has two choices. She can either borrow money at 7% per 41. Suppose Ms. Lee is buying a new house and must borrow \$150,000. She wants a

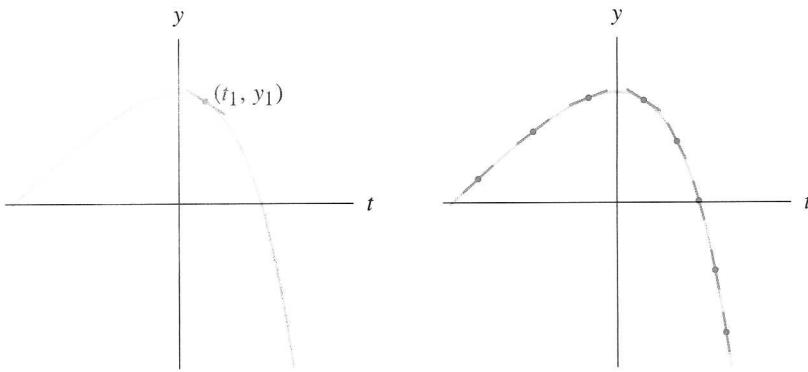


Figure 1.9
Slope of the tangent at the point (t_1, y_1)
is given by the value of $f(t_1, y_1)$.

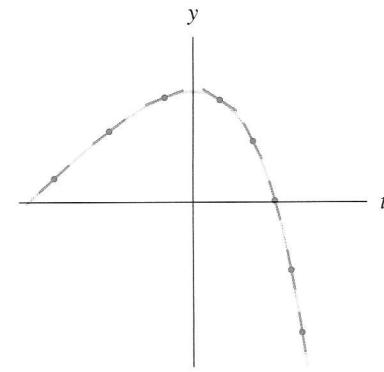


Figure 1.10
If $y = y(t)$ is a solution, then the slope
of any tangent must equal $f(t, y)$.

Slope Fields

This simple geometric observation leads to our main device for the visualization of the solutions to a first-order differential equation

$$\frac{dy}{dt} = f(t, y).$$

If we are given the function $f(t, y)$, we obtain a rough idea of the graphs of the solutions to the differential equation by sketching its corresponding **slope field**. We make this sketch by selecting points in the ty -plane and computing the numbers $f(t, y)$ at these points. At each point (t, y) selected, we use $f(t, y)$ to draw a minitangent line whose slope is $f(t, y)$ (see Figure 1.11). These minitangent lines are also called slope marks. Once we have a lot of slope marks, we can visualize the graphs of the solutions. For example, consider the differential equation

$$\frac{dy}{dt} = y - t.$$

In other words, the right-hand side of the differential equation is given by the function $f(t, y) = y - t$. To get some practice with the idea of a slope field, we sketch its slope field by hand at a small number of points. Then we discuss a computer-generated version of this slope field.

Generating slope fields by hand is tedious, so we consider only the nine points in the ty -plane. For example, at the point $(t, y) = (1, -1)$, we have $f(t, y) = f(1, -1) = -1 - 1 = -2$. Therefore we sketch a “small” line segment with slope -2 centered at the point $(1, -1)$ (see Figure 1.12). To sketch the slope field for all nine points, we use the function $f(t, y)$ to compute the appropriate slopes. The results are summarized in Table 1.2. Once we have these values, we use them to give a sparse sketch of the slope field for this equation (see Figure 1.12).

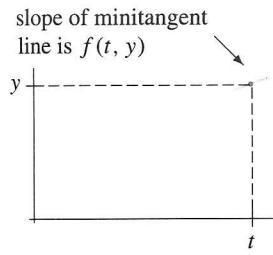
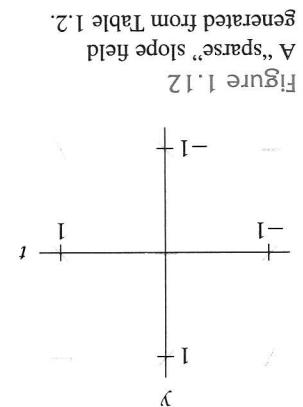


Figure 1.11
The slope of the minitangent
at the point (t, y) is
determined by the right-hand
side $f(t, y)$ of the
differential equation.



A “sparse” slope field generated from Table 1.2.

3. Note that each of these graphs is tangent to the slope field. Also note that, if $c = 0$, in Figure 1.14 we sketch the graphs of these functions with $c = -2, -1, 0, 1, 2$, functions are solutions.)

$\frac{dy}{dt} = 1 + ce^t$. Also $f(t, y) = y - t = (t + 1 + ce^t) - t = 1 + ce^t$. Hence all these check to see whether these functions are indeed solutions. If $y(t) = t + 1 + ce^t$, then though we have not studied the technique that gives us these solutions, we can still where c is an arbitrary constant. (At this point it is important to emphasize that, even

$$y(t) = t + 1 + ce^t,$$

this equation. We will see that the general solution consists of the family of functions In fact, in Section 1.8 we will learn an analytic technique for finding solutions of

increasing more and more rapidly. Solutions corresponding to initial conditions that are above the line seem to increase until they reach an absolute maximum. Solutions that are below this line seem to increase to initial conditions that pass through the points $(-1, 0)$ and $(0, 1)$. Solutions corresponding to initial line passing through the origin $(0, 0)$ are a diagonal in the t - y -plane. A glance at this slope field suggests that the graph of one solution is a diagonal in that region.

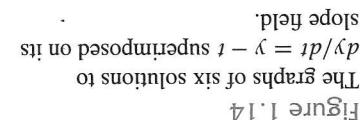
Skeching slope fields is best done using a computer. Figure 1.13 is a sketch of the slope field for this equation over the region $-3 \leq t \leq 3$ and $-3 \leq y \leq 3$ in the t - y -plane. We calculated values of the function $f(t, y)$ over 25×25 points (625 points)

(t, y)	$f(t, y)$	(t, y)	$f(t, y)$	(t, y)	$f(t, y)$	(t, y)	$f(t, y)$
$(-1, -1)$	-0	$(0, -1)$	-1	$(1, -1)$	-2	$(-1, 0)$	1
$(-1, 0)$	1	$(0, 0)$	0	$(1, 0)$	-1	$(-1, 1)$	2
$(-1, 1)$	2	$(0, 1)$	1	$(1, 1)$	0	$(-1, 2)$	3
$(-1, 3)$	3	$(0, 2)$	2	$(1, 2)$	1	$(-1, -2)$	-3
$(-1, -3)$	-3	$(0, -2)$	-2	$(1, -2)$	-1	$(-1, 1)$	1
$(-1, 1)$	1	$(0, 1)$	0	$(1, 1)$	-1	$(-1, -1)$	-1
$(-1, -1)$	-1	$(0, -1)$	0	$(1, -1)$	1	$(-1, 0)$	2
$(-1, 2)$	2	$(0, 2)$	1	$(1, 2)$	0	$(-1, -2)$	-2
$(-1, -2)$	-2	$(0, -2)$	-1	$(1, -2)$	0	$(-1, 3)$	3
$(-1, 3)$	3	$(0, 3)$	2	$(1, 3)$	1	$(-1, -3)$	-3

Selected slopes corresponding to the differential equation $\frac{dy}{dt} = y - t$

Table 1.2

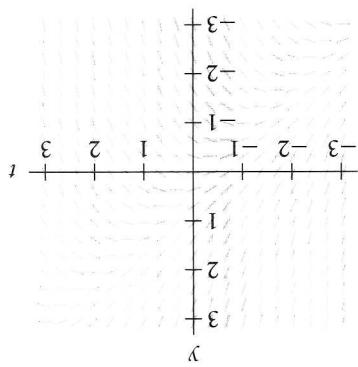
A computer-generated version of the slope field for $\frac{dy}{dt} = y - t$.



slope field.

The graphs of six solutions to

Figure 1.13



the graph is a straight line whose slope is 1. It goes through the points $(-1, 0)$ and $(0, 1)$.

Important Special Cases

From an analytic point of view, differential equations of the forms

$$\frac{dy}{dt} = f(t) \quad \text{and} \quad \frac{dy}{dt} = f(y)$$

are somewhat easier to consider than more complicated equations because they are separable. The geometry of their slope fields is equally special.

Slope fields for $dy/dt = f(t)$

If the right-hand side of the differential equation in question is solely a function of t , or in other words, if

$$\frac{dy}{dt} = f(t),$$

the slope at any point is the same as the slope of any other point with the same t -coordinate (see Figure 1.15).

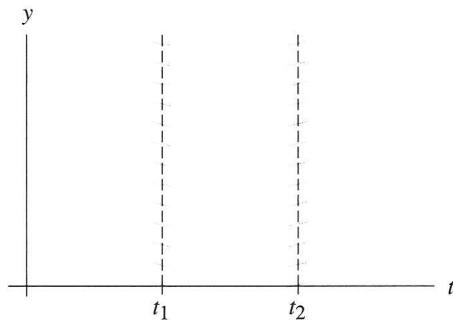


Figure 1.15

If the right-hand side of the differential equation is a function of t alone, then the slope marks in the slope field are determined solely by their t -coordinate.

Geometrically, this implies that all of the slope marks on each vertical line are parallel. Whenever a slope field has this geometric property for all vertical lines throughout the domain in question, we know that the corresponding differential equation is really an equation of the form

$$\frac{dy}{dt} = f(t).$$

(Note that finding solutions to this type of differential equation is the same thing as finding an antiderivative of $f(t)$ in calculus.)

For example, consider the slope field shown in Figure 1.16. We generated this slope field from the equation

$$\frac{dy}{dt} = 2t,$$

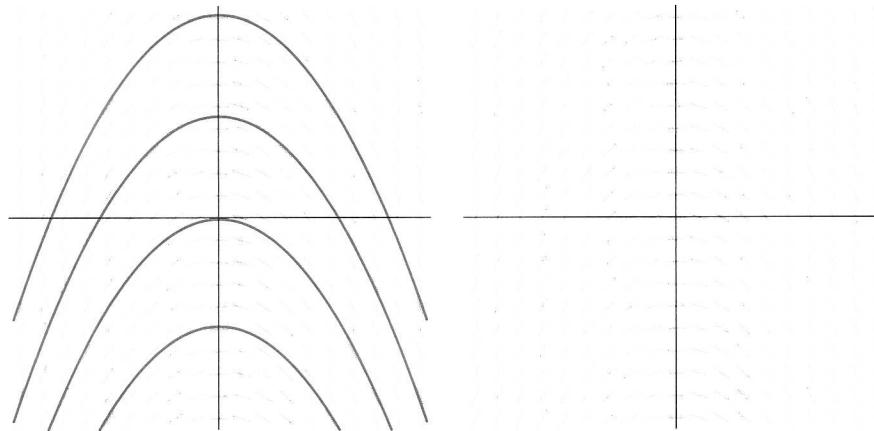
the right-hand side of the equation does not depend on the independent variable t . The slope field in this case is also somewhat special. Here, the slopes that correspond to two different points with the same y -coordinate are equal. That is, $f(t_1, y) = f(t_2, y)$ (see Figure 1.18).

In other words, the slope field of an autonomous equation is parallel along each horizontal line (y) since the right-hand side of the differential equation depends only on y . In other words, the right-hand side of the differential equation is parallel along each horizontal line (y) since the right-hand side of the differential equation depends only on y .

$$\frac{dy}{dt} = f(y),$$

In the case of an autonomous differential equation
Slope fields for autonomous equations

Figure 1.16 A slope field with parallel slopes along vertical lines.
Figure 1.17 Graphs of solutions to $\frac{dy}{dt} = 2t$ superimposed on its slope field.



In Figure 1.17 we have superimposed graphs of such solutions on this field. Note that all of these graphs simply differ by a vertical translation. If one graph is tangent to the slope field—by translating the original graph either up or down, we can get infinitely many graphs—all tangent to the slope field—by the slope field, we can get infinitely many graphs—all tangent to the slope field—by all of these graphs simply differ by a vertical translation.

Note that in this case the slope field is parallel to the y -axis. Hence the general solution to the differential equation consists of functions of the form

$$y(t) = t^2 + c,$$

where c is the constant of integration. Hence the general solution of the differential

$$y(t) = \int 2t \, dt = t^2 + c,$$

and from calculus we know that

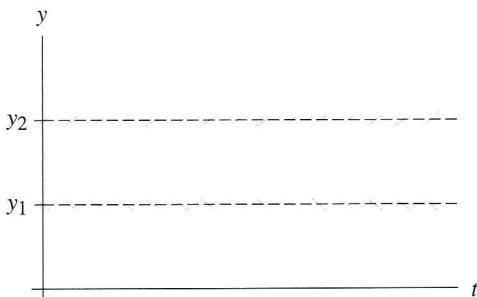


Figure 1.18
If the right-hand side of the differential equation is a function of y alone, then the slope marks in the slope field are determined solely by their y -coordinate.

For example, the slope field for the autonomous equation

$$\frac{dy}{dt} = 4y(1 - y)$$

is given in Figure 1.19. Note that, along each horizontal line, the slope marks are parallel. In fact, if $0 < y < 1$, then dy/dt is positive, and the tangents suggest that a solution with $0 < y < 1$ is increasing. On the other hand, if $y < 0$ or if $y > 1$, then dy/dt is negative and any solution with either $y < 0$ or $y > 1$ is decreasing.

We have equilibrium solutions at $y = 0$ and at $y = 1$ since the right-hand side of the differential equation vanishes along these lines. The slope field is horizontal all along these two horizontal lines, and therefore we know that these lines are the graphs of solutions. Solutions whose graphs are between these two lines are increasing. Solutions that are above the line $y = 1$ or that are below the line $y = 0$ are decreasing (see Figure 1.20).

The fact that autonomous equations produce slope fields that are parallel along horizontal lines indicates that we can get infinitely many solutions from one solution

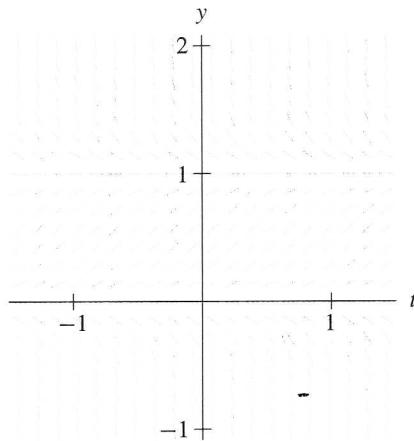


Figure 1.19
The slope field for $dy/dt = 4y(1 - y)$.

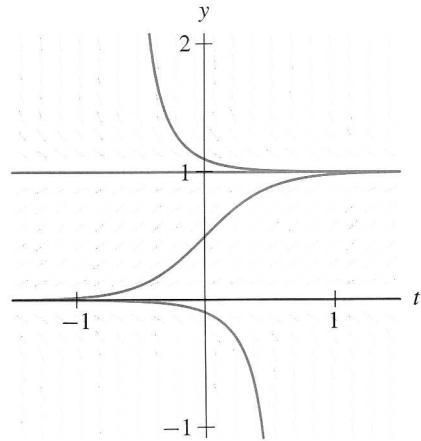


Figure 1.20
The graphs of five solutions superimposed on the slope field for $dy/dt = 4y(1 - y)$.

However, the integral on the left-hand side cannot be evaluated so easily. Thus we resort to qualitative methods. The right-hand side of this differential equation is positive except if $y = ny$ for any integer n . These special lines correspond to equilibrium

$$\int dt = \int \frac{dy}{\sin^2 y} e^{y^2/10}$$

We must evaluate the integrals

This equation is autonomous and hence separable. To solve this equation analytically,

$$\frac{dy}{dt} = e^{y^2/10} \sin^2 y.$$

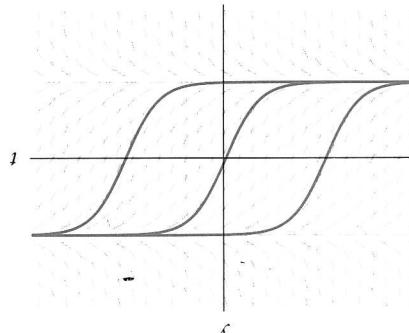
These ideas are especially important if the differential equation in question cannot be handled by analytic techniques. As an example, consider the differential equation

We could have used the analytic techniques of the previous section to find explicit formulas for the solutions. In fact, we can perform all of the required integrations to determine the general solution (see Exercise 15 on page 34). However, these integrations are complicated, and the formulas that result are by no means easy to interpret. This points out the power of geometric and qualitative methods for solving differential equations. Although with very little work, we gain a lot of insight into the behavior of solutions. Although we cannot use qualitative methods to answer specific questions, such as what the exact value of the solution is at any given time, we can use these methods to understand the long-term behavior of a solution.

$$\cdot(\lambda - 1)\lambda^t = \frac{dt}{\lambda p}$$

For the autonomous education

Analytic versus Qualitative Analysis



of the others.

The graphs of three solutions to an autonomous differential equation. Note that each is a horizontal translation of the other.

simply by translating the graph of the given solution left or right (see Figure 1.21). We will make extensive use of this simple geometric observation about the solutions to autonomous equations in Section 1.6.

solutions of the equation. Between these equilibria, solutions must always increase. From the slope field, we expect that their graphs either lie on one of the horizontal lines $y = n\pi$ or increase from one of these lines to the next higher as $t \rightarrow \infty$ (see Figure 1.22). Hence we can predict the long-term behavior of the solutions even though we cannot explicitly solve the equation.

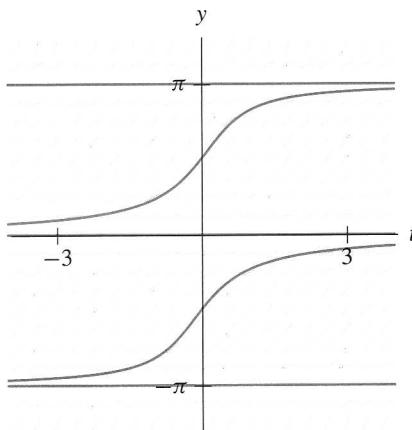


Figure 1.22
Slope field and graphs of solutions for

$$\frac{dy}{dt} = e^{y^2/10} \sin^2 y.$$

The lines $y = n\pi$ correspond to equilibrium solutions, and between these equilibria, solutions are increasing.

Although the computer pictures of solutions of this differential equation are convincing, some subtle questions remain. For example, how do we *really* know that these pictures are correct? In particular, for $dy/dt = e^{y^2/10} \sin^2 y$, how do we know that the graphs of solutions do not cross the horizontal lines that are the graphs of the equilibrium solutions (see Figure 1.22)? Such a solution could not cross these lines at a nonzero angle since we know that the tangent line to the solution must be horizontal. But what prevents certain solutions from crossing these lines tangentially and then continuing to increase?

In the differential equation

$$\frac{dy}{dt} = 4y(1-y)$$

we can eliminate these questions because we can evaluate all of the integrals and check the accuracy of the pictures using analytic techniques. But using analytic techniques to check our qualitative analysis does not work if we cannot find explicit solutions. Besides, having to resort to analytic techniques to check the qualitative results defeats the purpose of using these methods in the first place. In Section 1.5 we discuss powerful theorems that answer many of these questions without undue effort.

The Mixing Problem Revisited

Recall that in the previous section (page 32) we found precise analytic solutions for the differential equation

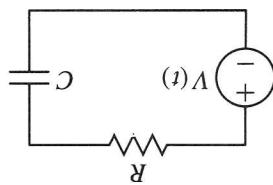
$$\frac{dS}{dt} = \frac{2000 - 3S}{100},$$

$$RC \frac{du_c}{dt} + u_c = V(t).$$

The quantities that specify the behavior of the circuit at a particular time t are the current $i(t)$ and the voltage $u_c(t)$ across the capacitor. From the theory of electric circuits, we know that $u_c(t)$ satisfies the differential equation in the voltage $u_c(t)$ across the capacitor. In this example we are interested in the design of the circuit.

The function that is specified by the circuit designer. In other words, we consider $V(t)$ to be a voltage with time such as alternating current. In any case, we could be a source that varies with time such as a constant source such as a battery, or it could be a source such as a voltage source across the capacitor. The input voltage source at time t is denoted by $V(t)$. This voltage source could be a voltage source at time t is denoted by $V(t)$ (the "capacitance"). The behavior of the capacitor is specified by a positive parameter C ("resistance"), and the behavior of the resistor is specified by a positive parameter R (the voltage source). The behavior of the capacitor is specified by a positive parameter R (the voltage source). The behavior of the resistor is specified by a positive parameter R (the voltage source). The simple electric circuit pictured in Figure 1.24 contains a capacitor, a resistor, and a voltage source.

Figure 1.24
Circuit diagram with resistor, capacitor, and voltage source.



An RC Circuit

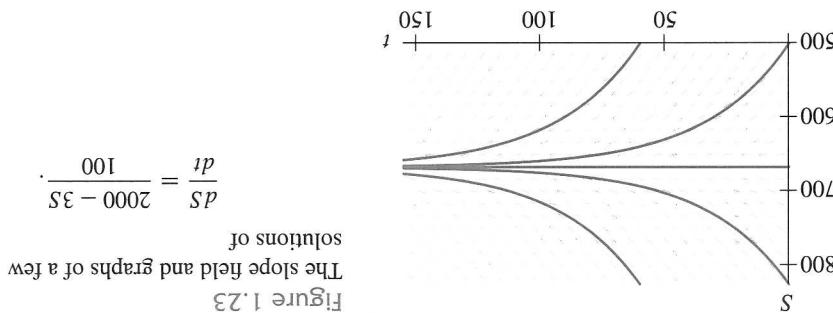


Figure 1.23
The slope field and graphs of a few solutions of

$$\frac{dS}{dt} = \frac{3S}{2000 - 3S}.$$

Using the slope field of this equation, we can easily derive a qualitative description. Here c is an arbitrary constant. We expect solutions to tend toward the equilibrium solution as t increases. This qualitative analysis indicates that, no matter what the initial amount of sugar, the amount of sugar in the vat tends to $2000/3$ as $t \rightarrow \infty$. Of course, we obtain the same result in a geometric setting. Furthermore, in other examples, taking such a limit may not be as easy as in this case, but qualitative methods may still be used to determine the long-term behavior of the solutions.

$$S(t) = ce^{-0.03t} + \frac{3}{2000},$$

solution of this equation was

where S describes the amount of sugar in a vat at time t . We found that the general

If we rewrite this in our standard form $dv_c/dt = f(t, v_c)$, we have

$$\frac{dv_c}{dt} = \frac{V(t) - v_c}{RC}.$$

We use slope fields to visualize solutions for four different types of voltage sources $V(t)$. (If you don't know anything about electric circuits, don't worry; Paul, Bob, and Glen don't either. In examples like this, all we need to do is accept the differential equation and "go with it.")

Zero input

If $V(t) = 0$ for all t , the equation becomes

$$\frac{dv_c}{dt} = -\frac{v_c}{RC}.$$

A sample slope field for a particular choice of R and C is given in Figure 1.25. We see clearly that all solutions "decay" toward $v_c = 0$ as t increases. If there is no voltage source, the voltage across the capacitor $v_c(t)$ decays to zero. This prediction for the voltage agrees with what we obtain analytically since the general solution of this equation is $v_c(t) = v_0 e^{-t/RC}$, where v_0 is the initial voltage across the capacitor. (Note that this equation is essentially the same as the exponential growth model that we studied in Section 1.1, and consequently, we can solve it analytically by either guessing the correct form of a solution or by separating variables.)

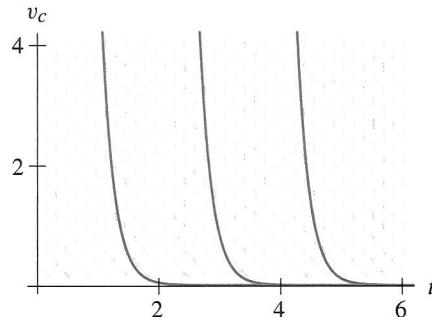


Figure 1.25
Slope field for

$$\frac{dv_c}{dt} = -\frac{v_c}{RC}$$

with $R = 0.2$ and $C = 1$, and the graph of three solutions.

Constant nonzero voltage source

Suppose $V(t)$ is a nonzero constant K for all t . The equation for voltage across the capacitor becomes

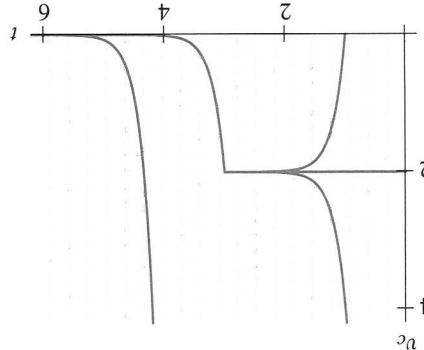
$$\frac{dv_c}{dt} = \frac{K - v_c}{RC}.$$

This equation is autonomous with one equilibrium solution at $v_c = K$. The slope field for this equation shows that all solutions tend toward this equilibrium as t increases (see Figure 1.26). Given any initial voltage $v_c(0)$ across the capacitor, the voltage $v_c(t)$ tends to the value $v = K$ as time increases.

for $V(t)$, which "turns off" at $t = 3$ for $R = 0.2$, $C = 1$, and $K = 2$, along with several solutions with different initial conditions.

$$\frac{du_c}{dt} = \frac{RC}{V(t) - u_c}$$

Slope field for
Figure 1.27



The right-hand side is given by two different formulas depending on the value of t . We can see this in the slope field for this equation (see Figure 1.27). It resembles Figures 1.25 and 1.26 pasted together along $t = 3$. Since the differential equation is not defined at $t = 3$, we must add an additional assumption to our model. We assume that the voltage $u_c(t)$ is a continuous function at $t = 3$. We could find formulas for the solution for $t < 3$, but for $t > 3$ it decays exponentially. Solutions with $u_c(0) \neq K$ move toward K for $t < 3$, but then decay toward zero for $t > 3$. We could find formulas for the solutions but for $t > 3$ it decays exponentially. Solutions with $u_c(0) = K$ is constant for $t < 3$, The particular solution with the initial condition $u_c(0) = K$ is continuous at $t = 3$.

$$\frac{du_c}{dt} = \left\{ \begin{array}{ll} \frac{RC}{K - u_c} & \text{for } 0 \leq t < 3; \\ \frac{RC}{V(t) - u_c} & \text{for } t > 3. \end{array} \right.$$

Suppose $V(t) = K > 0$ for $0 \leq t < 3$, but at $t = 3$, this voltage is "turned off." Then $V(t) = 0$ for $t > 3$. Our differential equation is

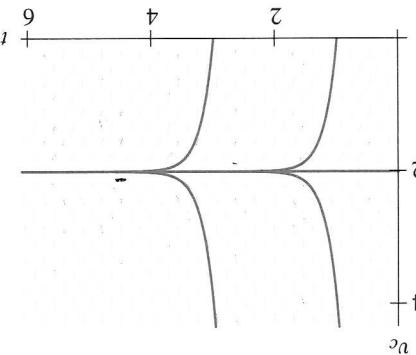
On-Off Voltage Source

We could find a formula for the general solution by separating variables and integrating, but we leave this as an exercise.

for $R = 0.2$, $C = 1$, and $K = 2$, and the graphs of several solutions with different initial conditions.

$$\frac{du_c}{dt} = \frac{RC}{K - u_c}$$

Slope field for
Figure 1.26



by first finding the solution for $t < 3$, then starting over for $t > 3$ (see Section 1.2), but we again leave this as an exercise.

Periodic on-off voltage source

Suppose $V(t)$ alternates periodically between the values K and zero every three seconds. That is,

$$V(t) = \begin{cases} K & \text{for } 0 \leq t < 3; \\ 0 & \text{for } 3 < t < 6; \\ K & \text{for } 6 < t < 9; \\ \vdots & \end{cases}$$

This corresponds to someone switching the source voltage off every three seconds and back on three seconds later. The slope field for the differential equation

$$\frac{dv_c}{dt} = \frac{V(t) - v_c}{RC}$$

is given in Figure 1.28. Parts of the slope fields in Figures 1.25 and 1.26 are patched together every three seconds. The solutions are also patched together from these two equations. When $V(t) = K$, the solution approaches the equilibrium value $v_c = K$, and when $V(t) = 0$, the solution decays toward zero.

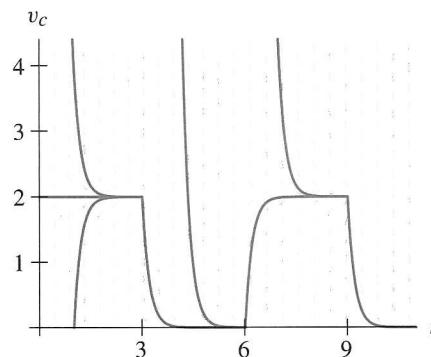


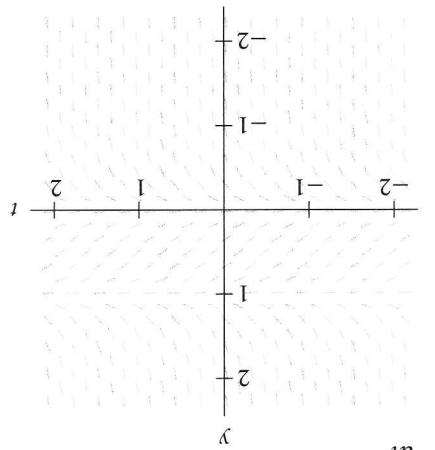
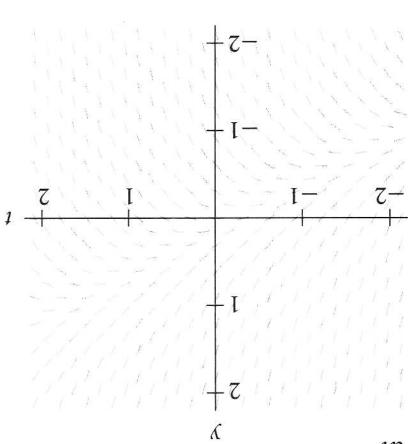
Figure 1.28
Slope field for

$$\frac{dv_c}{dt} = \frac{V(t) - v_c}{RC}$$

where $V(t)$ alternates between K and zero every three seconds for $R = 0.2$, $C = 1$, and $K = 2$, along with the graphs of several solutions with different initial conditions.

Combining Qualitative with Quantitative Results

When only knowledge of the qualitative behavior of the solution is required, sketches of solutions obtained from slope fields can sometimes suffice. In other applications it is necessary to know the exact value (or almost exact value) of the solution with a given initial condition. In these situations analytic and/or numerical methods can't be avoided. But even then, it is nice to have a picture of what solutions look like.



$$7. \frac{dy}{dt} = 3y(1-y) \quad 8. \frac{dy}{dt} = 2y - t$$

You should confirm your answer using HPGSOLVER. You should first answer these exercises without using any technology, and then you

(b) describe briefly the behavior of the solution with $y(0) = 1/2$ as t increases.

(a) sketch a number of different solutions on the slope field, and

each equation,

In Exercises 7–10, a differential equation and its associated slope field are given. For

$$1. \frac{dy}{dt} = t^2 - t \quad 2. \frac{dy}{dt} = 1 - y \quad 3. \frac{dy}{dt} = y + t + 1$$

$$4. \frac{dy}{dt} = t^2 + 1 \quad 5. \frac{dy}{dt} = 2y(1-y) \quad 6. \frac{dy}{dt} = 4y^2$$

note to the student that precedes the Table of Contents.
For more details about HPGSOLVER and other programs that are on the CD, see the

confirm your answer in part (b).

(c) Imagine a more detailed drawing of the slope field and then use HPGSOLVER to

(b) Use HPGSOLVER to check your drawing.

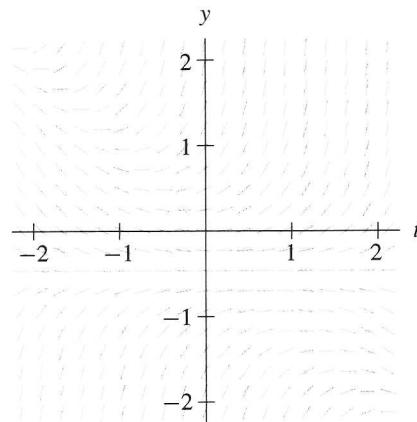
associated slope marks without the use of technology.

(a) Pick a few points (t, y) with both $-2 \leq t \leq 2$ and $-2 \leq y \leq 2$ and plot the

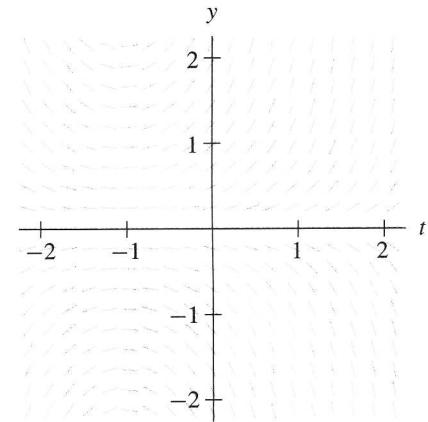
In Exercises 1–6, sketch the slope fields for the given differential equation as follows:

EXERCISES FOR SECTION 1.3

9. $\frac{dy}{dt} = \left(y + \frac{1}{2}\right)(y + t)$



10. $\frac{dy}{dt} = (t + 1)y$



11. Suppose we know that the function $f(t, y)$ is continuous and that $f(t, 3) = -1$ for all t .

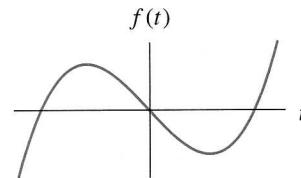
- (a) What does this information tell us about the slope field for the differential equation $dy/dt = f(t, y)$?
 (b) What can we conclude about solutions $y(t)$ of $dy/dt = f(t, y)$? For example, if $y(0) < 3$, can $y(t) \rightarrow \infty$ as t increases?

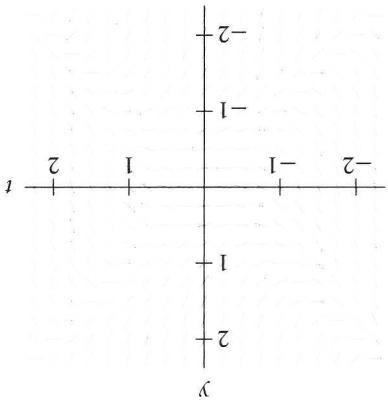
12. Consider the autonomous differential equation

$$\frac{dS}{dt} = S^3 - 2S^2 + S.$$

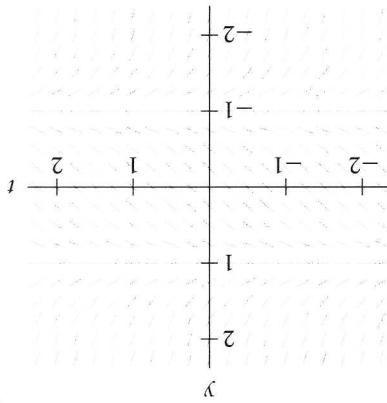
- (a) Make a rough sketch of the slope field without the use of any technology.
 (b) Using this drawing, sketch the graphs of the solutions $S(t)$ with the initial conditions $S(0) = 0$, $S(0) = 1/2$, $S(1) = 1/2$, $S(0) = 3/2$, and $S(0) = -1/2$.
 (c) Confirm your answer using HPGSolver.

13. Suppose we know that the graph to the right is the graph of the right-hand side $f(t)$ of the differential equation $dy/dt = f(t)$. Give a rough sketch of the slope field that corresponds to this differential equation.

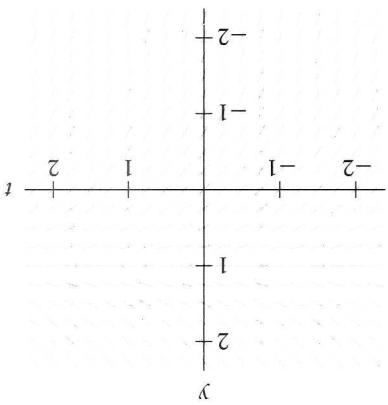




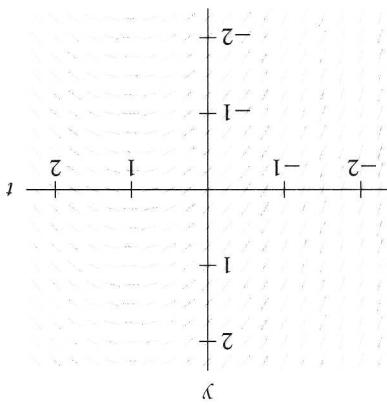
(p)



(c)



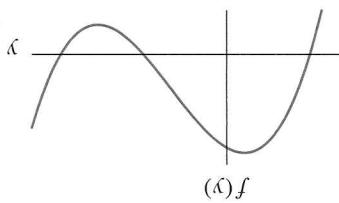
(q)



(a)

$$\begin{aligned}
 & (\text{v}) \quad \frac{dy}{dt} = 1 - y \quad (\text{vi}) \quad \frac{dy}{dt} = t^2 - y^2 \quad (\text{vii}) \quad \frac{dy}{dt} = 1 + y \quad (\text{viii}) \quad \frac{dy}{dt} = y^2 - t^2 \\
 & (\text{i}) \quad \frac{dy}{dt} = t - 1 \quad (\text{ii}) \quad \frac{dy}{dt} = 1 - y^2 \quad (\text{iii}) \quad \frac{dy}{dt} = y^2 - t^2 \quad (\text{iv}) \quad \frac{dy}{dt} = 1 - t
 \end{aligned}$$

15. Eight differential equations and four slope fields are given below. Determine the choice is correct. You should do this exercise without using technology.
- equation that corresponds to each slope field and state briefly how you know your

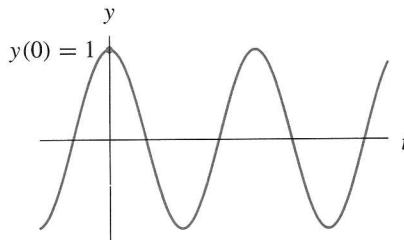


14. Suppose we know that the graph to the right is the graph of the right-hand side $f'(y)$ of the differential equation $\frac{dy}{dt} = f(y)$. Give a rough sketch of the differential equation $\frac{dy}{dt} = f(y)$ that corresponds to this slope field.

16. Suppose we know that the graph below is the graph of a solution to $dy/dt = f(t)$.

- (a) How much of the slope field can you sketch from this information? [Hint: Note that the differential equation depends only on t .]

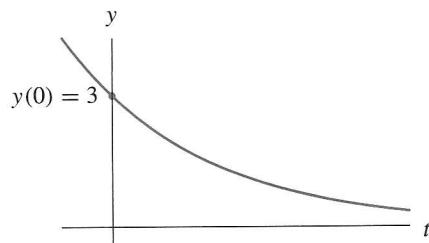
- (b) What can you say about the solution with $y(0) = 2$? (For example, can you sketch the graph of this solution?)



17. Suppose we know that the graph below is the graph of a solution to $dy/dt = f(y)$.

- (a) How much of the slope field can you sketch from this information? [Hint: Note that the equation is autonomous.]

- (b) What can you say about the solution with $y(0) = 2$? Sketch this solution.



18. Suppose the constant function $y(t) = 2$ for all t is a solution of the differential equation

$$\frac{dy}{dt} = f(t, y).$$

- (a) What does this tell you about the function $f(t, y)$?
 (b) What does this tell you about the slope field? In other words, how much of the slope field can you sketch using this information?
 (c) What does this tell you about solutions with initial conditions $y(0) \neq 2$?

Exercises 19–23 refer to the RC circuit discussed in this section. The differential equation for the voltage v_c across the capacitor is

$$\frac{dv_c}{dt} = \frac{V(t) - v_c}{RC}.$$

19. Find the formula for the general solution of the RC circuit equation above if the voltage source is constant for all time. In other words, $V(t) = K$ for all t . (Your solution will contain the three parameters, R , C , and K , along with a constant that depends on the initial condition.)