

(coefficients) whose eigenvalues will be real.

Each problem is worth 10 points. For full credit provide complete justification for your answers.

1. If you know that $\lambda_1 = -3$ and $\lambda_2 = -2$ are eigenvalues of the coefficient matrix of a planar linear system, and that $\mathbf{V}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ and $\mathbf{V}_2 = \begin{pmatrix} -1 \\ 3 \end{pmatrix}$ are the corresponding eigenvectors, write a general solution to the system.

$$\boxed{Y(t) = k_1 e^{-3t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + k_2 e^{-2t} \begin{pmatrix} -1 \\ 3 \end{pmatrix}} \quad \text{Yep}$$

4. Sketch the phase portrait for a system of plane differential equations where $\lambda_1 = -3$ and $\lambda_2 = -1$ with $\mathbf{V}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ and $\mathbf{V}_2 = \begin{pmatrix} -1 \\ 3 \end{pmatrix}$ being the corresponding eigenvectors.

2. Give an example of a coefficient matrix for a planar linear system in which the origin would be classified as a saddle.

$$\lambda^2 - 2\lambda - 3 = 0$$

$$(\lambda - 3)(\lambda + 1) = 0$$

$$\lambda = -1, 3 \quad \text{one } \underline{\lambda \text{ is positive}} \text{ and } \underline{\lambda \text{ is negative}}$$

$$\lambda - 3 \rightarrow 3 - \lambda \quad \lambda + 1 \rightarrow -1 - \lambda$$

$$A = \boxed{\begin{pmatrix} 3 & 0 \\ 0 & -1 \end{pmatrix}} \quad \text{Nice}$$

3. Give an example of a system of two linear differential equations (with real coefficients) whose eigenvalues will be complex.

For that to happen, the discriminant must be ≤ 0
 $(b^2 - 4ac)$

so we want to make a or c bigger compared
 to b^2 and their product $-ac$.

so, $A = \begin{pmatrix} -1 & 40 \\ -1 & -1 \end{pmatrix}$ ought to be such a system

so, $\frac{dx}{dt} = -1x + 40y$ Ans.
 and $\frac{dy}{dt} = -1x - 1y$

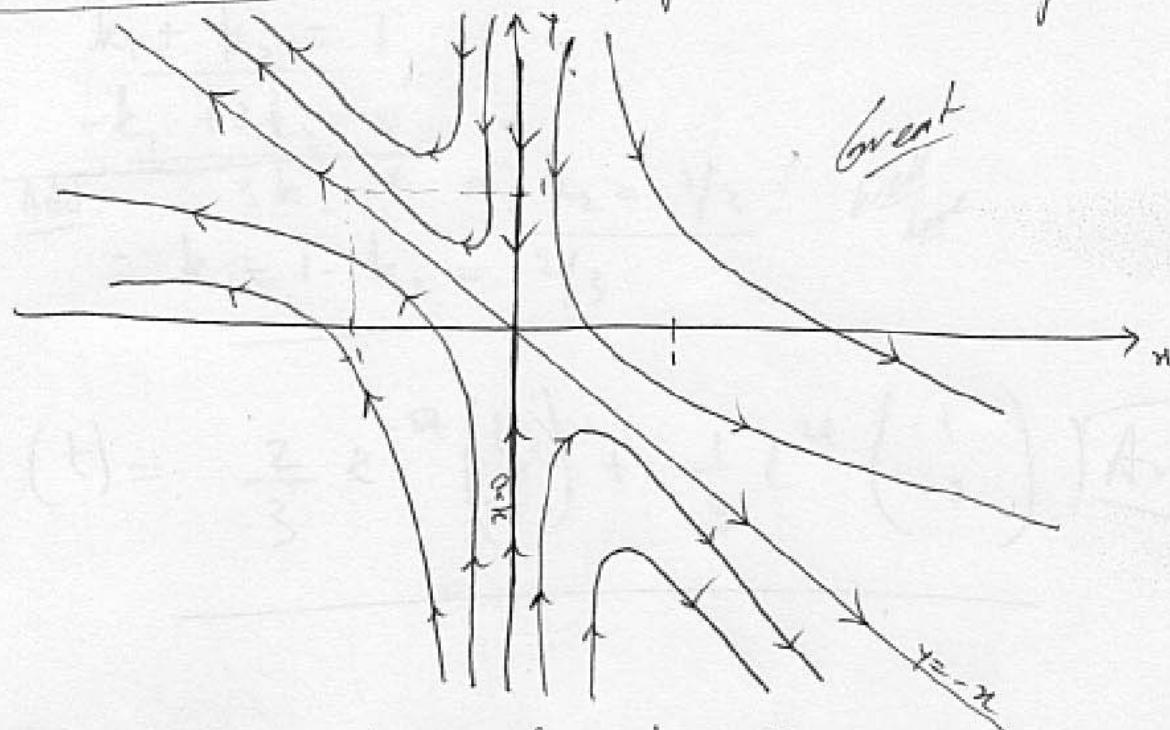
Handwavy, but totally valid.

Check: $\begin{vmatrix} -1-\lambda & 40 \\ -1 & -1-\lambda \end{vmatrix} = 0 \Rightarrow (\lambda+1)^2 + 40 = 0 \Rightarrow \lambda^2 + 2\lambda + 41 = 0$
 and $2^2 - 4 \cdot 41 < 0$.

4. Sketch the phase portrait for a system of planar differential equations where $\lambda_1 = -2$ and $\lambda_2 = -4$.

1, with $\mathbf{V}_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ and $\mathbf{V}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ being the corresponding eigenvectors.

So, we have a saddle! Along \mathbf{V}_1 , curves move towards $(0, 0)$ and away from $(0, 0)$ along \mathbf{V}_2 . Exactly.



They come along \mathbf{V}_1 and walk away along \mathbf{V}_2 .

5. Given that the planar system

$$\frac{d\mathbf{Y}}{dt} = \begin{pmatrix} -4 & 1 \\ 2 & -3 \end{pmatrix} \mathbf{Y}$$

has general solution

$$\mathbf{Y}(t) = k_1 e^{-5t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + k_2 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix},$$

find the particular solution satisfying $\mathbf{Y}_0 = (1, 0)$.

$$\vec{\gamma}(0) = k_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} + k_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} k_1 \\ -k_1 \end{pmatrix} + \begin{pmatrix} k_2 \\ 2k_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\frac{k_1 + k_2}{k_1 + 2k_2} = 1 \quad ; \quad k_1 = 1 - k_2$$

$$-k_1 + 2k_2 = 0$$

$$-(1 - k_2) + 2k_2 = 0$$

$$-1 + k_2 + 2k_2 = 0$$

Well done!

$$3k_2 = 1$$

$$k_2 = \frac{1}{3} \quad ; \quad k_1 = 1 - \frac{1}{3} = \frac{2}{3}$$

$$\boxed{\vec{\gamma}(t) = \frac{2}{3} e^{-5t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + \frac{1}{3} e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}}$$

6. Give a general solution to the system of differential equations

$$\frac{dx}{dt} = 2x + 0y$$

$$\frac{dy}{dt} = 4x - 3y$$

$$A = \begin{pmatrix} 2 & 0 \\ 4 & -3 \end{pmatrix} \quad Y = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{pmatrix} 2 & 0 \\ 4 & -3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \lambda \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\det(A - \lambda I) = 0$$

$$\det \begin{pmatrix} 2-\lambda & 0 \\ 4 & -3-\lambda \end{pmatrix} = 0$$

$$(2-\lambda)(-3-\lambda) - 0 = 0$$

$$-6 - 2\lambda + 3\lambda + \lambda^2 = 0$$

$$\lambda^2 + \lambda - 6 = 0$$

$$(\lambda + 3)(\lambda - 2) = 0$$

$$\lambda = 2, -3$$

For $\lambda = 2$:

$$2x = 2x$$

$$4x - 3y = 2y \rightarrow 4x = 5y \quad \left(\begin{array}{l} \frac{5}{4} \\ 1 \end{array} \right)$$

$$x = \frac{5}{4}y$$

Excellent

For $\lambda = -3$

$$2x = -3x$$

$$4x - 3y = -3y \rightarrow 4x = 0 \quad \left(\begin{array}{l} 0 \\ 1 \end{array} \right)$$

$$x = 0$$

$$Y(t) = k_1 e^{2t} \begin{pmatrix} \frac{5}{4} \\ 1 \end{pmatrix} + k_2 e^{-3t} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad \text{or}$$

$$Y(t) = k_1 e^{2t} \begin{pmatrix} \frac{5}{4} \\ 1 \end{pmatrix} + k_2 e^{-3t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

7. Give a condition under which the planar system associated with the differential equation

$$ay'' + by' + cy = 0$$

will have purely imaginary eigenvalues.

$$e^{st} (as^2 + bs + c) = 0$$

so

$$as^2 + bs + c = 0$$

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

purely
imaginary when $b=0$

so

$$\frac{\pm \sqrt{-4ac}}{2a}$$

Nice

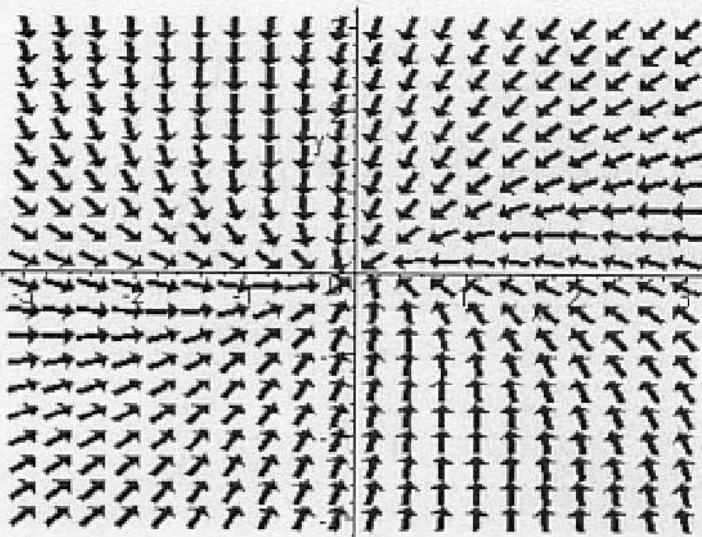
and $a+c$ are both + or -

8. For the planar system the form

$$\frac{d\mathbf{Y}}{dt} = \begin{pmatrix} -2 & -1 \\ 1 & -4 \end{pmatrix} \mathbf{Y},$$

Find the particular solution satisfying the initial condition $\mathbf{Y}_0 = (0, 1)$.

with $b = 0$ must have complex eigenvalues.



$$\vec{A} = \begin{pmatrix} -2 & -1 \\ 1 & -4 \end{pmatrix}$$

$$\det \begin{pmatrix} -2-\lambda & -1 \\ 1 & -4-\lambda \end{pmatrix} = 0$$

$$\left. \begin{array}{l} (2+\lambda)(4+\lambda) + 1 = 0 \\ 8 + 4\lambda + 2\lambda + \lambda^2 + 1 = 0 \\ \lambda^2 + 6\lambda + 9 = 0 \end{array} \right\}$$

$$(\lambda + 3)^2 = 0$$

repeated eigenvalue $\lambda = -3$

$$\vec{V}_1 = (\vec{A} - \lambda \vec{I}) \vec{V}_0 \rightarrow \left(\begin{pmatrix} -2 & -1 \\ 1 & -4 \end{pmatrix} - \begin{pmatrix} -3 & 0 \\ 0 & -3 \end{pmatrix} \right) \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\vec{V}_0 = (x_0, y_0) = (0, 1)$$

$$\vec{Y}(t) = e^{-3t} \vec{V}_0 + t e^{-3t} \vec{V}_1$$

~~$$\text{Well done } \left(\begin{pmatrix} -2 & -1 \\ 1 & -4 \end{pmatrix} + \begin{pmatrix} 3 & 0 \\ 0 & 3 \end{pmatrix} \right) \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$~~

$$\boxed{\vec{Y}(t) = e^{-3t} \begin{pmatrix} 0 \\ 1 \end{pmatrix} + t e^{-3t} \begin{pmatrix} -1 \\ -1 \end{pmatrix}}$$

$$\begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

$$(2 \times 2) \times (2 \times 1) = (2 \times 1)$$

9. Show that a system of the form

$$\frac{dx}{dt} = ax + by$$

$$\frac{dy}{dt} = -bx + ay$$

with $b \neq 0$ must have complex eigenvalues.

$$\begin{pmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{pmatrix} = \begin{pmatrix} a & b \\ -b & a \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad d\bar{Y} = A\bar{Y}$$

$$\det \begin{pmatrix} a-\lambda & b \\ -b & a-\lambda \end{pmatrix} = 0$$

$$(a-\lambda)(a-\lambda) + b^2 = 0$$

$$a^2 - 2a\lambda + \lambda^2 + b^2 = 0$$

$$\lambda^2 - 2a\lambda + (a^2 + b^2) = 0$$

$a=1$
 $b=2a$ for quadratic equation.
 $c=a^2+b^2$

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \rightarrow \frac{2a \pm \sqrt{4a^2 - 4(a^2 + b^2)}}{2} \rightarrow \frac{2a \pm \sqrt{4a^2 - 4a^2 - 4b^2}}{2}$$

$$\frac{2a \pm \sqrt{-4b^2}}{2} \rightarrow \frac{2a \pm 2\sqrt{-b^2}}{2} \rightarrow \underline{\underline{a \pm \sqrt{-b^2}}}$$

b^2 itself will always be positive so $-b^2$ will always be negative.

Therefore since the discriminant is less than zero, the system must have complex eigenvalues.

Outstanding!

10. Let

$$\mathbf{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

Define the trace of \mathbf{A} to be $\text{tr}(\mathbf{A}) = a + d$. Show that \mathbf{A} has only one eigenvalue if and only if $(\text{tr}(\mathbf{A}))^2 - 4\det(\mathbf{A}) = 0$.

$$\underline{(a-\lambda)(d-\lambda) - bc = 0}$$

$$\underline{ad - \lambda d - \lambda a + \lambda^2 - bc = 0}$$

$$\underline{\lambda^2 - (a+d)\lambda + ad - bc = 0}$$

$$\underline{\lambda^2 - (a+d)\lambda + ad - bc}$$

$$D \quad \underline{\frac{a+d \pm \sqrt{(a+d)^2 - 4(ad-bc)}}{2}}$$

has 1 eigenvalue iff $\underline{(a+d)^2 - 4(ad-bc)} = 0$ since $\frac{(a+d) \pm 0}{2}$

$$(a+d) = \text{tr}(\mathbf{A})$$

$$\det(\mathbf{A}) = ad - bc \quad \text{so}$$

$$\underline{(a+d)^2 - 4(ad-bc)} = \underline{\text{tr}(\mathbf{A})^2 - 4\det(\mathbf{A})}$$

Nice
 $\frac{a+b}{2}$

$$\underline{\text{tr}(\mathbf{A})^2 - 4\det(\mathbf{A}) = 0 \text{ as well}}$$

$$\Rightarrow A \text{ can only have 1 eigenvalue namely } \lambda = \frac{a+d}{2}$$